#### **Consider This Set Covering Problem**

#### I claim I can solve this by inspection

#### **Now I Start Throwing Things Away ...**



The first and last constraints are redundant – why?



Answer: 
$$x_1 = 1$$
,  $x_2 = 1$ ,  $x_6 = 1$ ,  $z = 4$ 

#### **Presolve and Node Reductions**

- An important feature of commercial codes is presolve
  - Looks at problem structure, particularly binary variables
  - Uses various techniques to reduce the problem
  - Can be applied at any node in a branch-and-bound tree
- These techniques are responsible for much recent improvement in MIP codes
- Following is a (partial) set of rules for cover (>=) and partition (=) problems
  - Note: can covert a pack to a partition by adding slack variables
  - Then, use the rules for a partition
  - These rules assume the  $C_i$ 's are all > 0

#### **Reduction Rules**

 (1) (cover, partition): If all A<sub>ij</sub>'s are 0 in row i, the problem's infeasible

| cover     | 0 | 0 | 0 | 0 | 0 | 0 | ≥1 |
|-----------|---|---|---|---|---|---|----|
| partition | 0 | 0 | 0 | 0 | 0 | 0 | =1 |

• (2)(cover, partition) If row i has 1 nonzero  $A_{ij}$  (say,  $A_{ik}$ ), then set  $x_{ik} = 1$ , delete column k, and delete all rows r with  $A_{rk} = 1$ :



#### **More Reduction Rules**

• (2a) (partition) In addition to the row deletions in (2), delete every column where  $A_{tj} = A_{tk} = 1$ , j <> k, for every row r deleted

(3) (cover, partition) If A<sub>rj</sub> >= A<sub>ij</sub> for all j for rows r and i, delete row r

#### **Yet More Reduction Rules**

- (3a) (partition) As in (3), but also delete all columns with  $A_{rk} = 1$  and  $A_{ik} = 0$ One of these (*r*) 0 0 1 () variables will be = 1, forces *(i)* 0 0 0 0 0 all others to 0
- (4) (cover, partition) If **S** is a set of columns, and

$$\sum_{j \in S} A_{ij} = A_{ik} \text{ for all } i,$$
  
  $k \notin S, \text{ and } \sum_{j \in S} C_j \leq C_k$ 

then, delete column  $\boldsymbol{k}$ 

OR 541 Fall 2009 Lesson 11-1, p. 6

#### Last of the Reductions

• Reduction (4):



• Reduction (4a) (cover) as in (4), but with condition

$$\sum_{j \in S} A_{ij} > A_{ik} \text{ for all } i$$

OR 541 Fall 2009 Lesson 11-1, p. 7



Rule 3: Delete row 2 (covered by row 1)

Rule 3: Delete row 4 (covered by row 3)

## Example (cont'd)

• No more reductions, but can you solve the problem?

row 1110000row 3001100row 5000111row 6010011

•  $x_2 = 1, x_4 = 1$ 

#### **Strong Versus Weak Formulations**

- An example from my past:
  - Job was associated with an airlift analysis
  - Had 100 possible onload locations in the U.S.
  - Needed to reduce locations to 10-20; all cargo from other locations would go to one of the chosen "hubs"
  - Wanted to minimize total tonnage\*distance to move cargo to hubs
  - Known as a "k-median" problem
- First used a heuristic on the problem
- Was learning GAMS at the time, so I set it up as an integer program

### **The First K-Median Formulation**

- Indicies
  - *i,j* = locations
- Data
  - **STONS**<sub>*i*</sub> = short tons to be moved from location *i*
  - **DIST**<sub>ij</sub> = distance between **i** and **j**
  - **MAXHUBS** = maximum number of hubs
  - **NUM** = total number of locations
- Variables
  - **assign**<sub>ij</sub> = 1 if location **i** assigned to hub **j**, 0 otherwise
  - choose<sub>j</sub> = 1 if location j chosen as a hub, 0 otherwise

#### **The First Model**

• Objective and constraints:

## **No Luck**

- Tried to solve this in OSL
  - Still didn't meet integrality gap requirements after 100,000 iterations
  - Ran for several hours
  - No progress
  - Went back to heuristic, wondered what I did wrong
- Asked an optimization professor a year later at a meeting
  - He sent back an answer the next day
  - His change allowed OSL to solve the problem in about 10 seconds
  - What was it?

### **A Stronger Formulation**

• All he suggested was the following:

$$\min z = \sum_{ij} DIST_{ij} * STONS_{ij} * assign_{ij}$$
  
subject to  
$$\sum_{j} assign_{ij} = 1 \text{ for all } i$$
  
$$\sum_{j} choose_{j} \leq MAXHUBS$$
  
$$assign_{ij} \leq choose_{j} \text{ for all } i, j$$
  
$$assign_{ij} \in \{0,1\} \text{ for all } i, j$$
  
$$choose_{j} \in \{0,1\} \text{ for all } j$$

- Note that this increased the number of constraints by 100 x 100 - 100 = 9900
- How could it be so much faster?

#### With MIPs, More Constraints Are Better

- The first formulation encouraged "fractionation" of the binary variables
- The second cuts off many possible fractional solutions
- Want to get as close to the "integer hull" as possible



OR 541 Fall 2009 Lesson 11-2 p. 6

#### **Another Strengthening Example**

• From the mining example:

$$o_{it} \ge o_{i,t+1}$$
 for all  $i, t < 5$   
 $e.g.,$   
 $o_{i1} \ge o_{i2}$   
 $o_{i2} \ge o_{i3}$   
:

• A stronger set of constraints:

$$o_{it} \ge o_{i,t'}$$
 for all  $i, t < 5, t' > t$   
 $e.g.,$   
 $o_{i1} \ge o_{i2}$   
 $o_{i1} \ge o_{i3}$   
 $o_{i1} \ge o_{i4}$   
 $o_{i1} \ge o_{i5}$   
 $o_{i2} \ge o_{i3}$   
:

### Cuts

- See Winston, Sec. 9-8
- Note that branching requires solving two LPs
  - One for the integer floor of the branching variable
  - One for the integer ceiling of the branching variable
- An alternative approach is called a *cut* 
  - The idea here is to "cut off" the fractional solution, but don't cut off any feasible integer solutions
  - The aim is to generate constraints that form the integer hull of the feasible region
  - Such constraints are called *facets*

## From the Dual Simplex Lesson (6-1)

• Recall this was the optimal (fractionated) tableau:

| Row | z | x1 | x2 | s1   | s2   | RHS  | BV |
|-----|---|----|----|------|------|------|----|
| 0   | 1 | 0  | 0  | 2/5  | 9/5  | 44/5 | Z  |
| 1   |   | 1  | 0  | -2/5 | 1/5  | 4/5  | x1 |
| 2   |   | 0  | 1  | 1/5  | -3/5 | 8/5  | x2 |

• Row 2 can be written as:

$$x_2 + \frac{1}{5}s_1 - \frac{3}{5}s_2 = \frac{8}{5}$$

• In Lesson 6-1, I used this row (called a *source row*) to generate a mysterious constraint; how did I do that?

## **Generating a Gomory Cut**

• We rewrite this constraint by recognizing that any fraction can be written as

 $x = \lfloor x \rfloor + f, 0 < f < 1$ 

• So, applying this to Row 2, we get:

$$x_2 + \left(0s_1 + \frac{1}{5}s_1\right) + \left(-s_2 + \frac{2}{5}s_2\right) = \left(1 + \frac{3}{5}\right)$$

• Now, group the integral terms on the left and the fractional terms on the right:

$$x_2 + 0s_1 - s_2 - 1 = -\frac{1}{5}s_1 - \frac{2}{5}s_2 + \frac{3}{5}$$

Part we would like to get rid of

## **Some Arguments**

- For integer feasibility:
  - The left-hand side must be integer
  - Therefore, the right-hand side must be integer
  - $\mathbf{s}_1$  and  $\mathbf{s}_2$  must be >= 0
- So, what's the biggest the right-hand side can be and still be feasible?
- Result: we add the cut:

$$-\frac{1}{5}s_1 - \frac{2}{5}s_2 + \frac{3}{5} \le 0, \text{ or}$$
$$-\frac{1}{5}s_1 - \frac{2}{5}s_2 + s_3 = -\frac{3}{5}$$

• Is this cool, or what?

#### More Info on Cuts

- Cutting plane algorithms had a bad reputation early
  - Algorithms only added one cut at a time
  - Had very slow convergence
- Have recently become very popular
  - No reason to add cuts one at a time
  - Can add a cut for virtually any fractional row
  - Can combine with branch-and-bound (branch on one variable, generate cuts for others)
  - Easy to implement, run very quickly
- Bixby article shows that installing these cuts in CPLEX gives tremendous improvements

# A (Very) Quick Tour of CPLEX MIP Switches

- For a small MIP or one known to be easy, you can stick with the defaults
- For anything else, you should *always* set the following:
  - Time limit (p. 95): CPLEX has a huge default (100,000,000 hours, a bit longer than I'd wait)
  - MIP strategy (p. 98): choose depth-first to emphasize feasibility, others to search for better solutions
  - Upper cutoff/lower cutoff (p. 106): *if you have a solution*, set these to avoid unproductive parts of the b-b tree
  - **Relative/absolute gap** (p. 106): a good starting relative gap is 0.10; absolute gap depends on the problem

## **CPLEX Switches You Can Play With**

- Bound strengthening, coefficient reduction (p. 90)
  - These are more aggressive prereduce options
  - You should consider them if you have lots of binary variables and "chains" of relationships
- MIP probing (p. 99)
  - Explores implications of binary settings at every node
  - Time consuming, but may crack the problem early
- Variable selection (p. 99)
  - Strong branching is "probing lite" can be very helpful
  - Maximum infeasibility branching is useful if you have feasible solutions and want to get faster improvement

## **CPLEX** Cuts

- CPLEX can employ 9 different types of cuts
  - Some are easy (like Gomory fractional cuts)
  - Some involve substantial math (disjunctive cuts)
  - Not easy to figure out a priori which will work
- Some general advice
  - CPLEX is fairly intelligent on when to apply cuts
  - If you're really having trouble, go aggressive on everything (kitchen sink approach)
  - Bixby's article gives good statistics on general performance of cuts on a large suite of MIPs
  - Clique cuts good for partition problems; cover cuts good for covers
  - Implied bound cuts good for problems with lots of general integer variables

### Conclusion

- Be prepared for a lot of work with a big MIP
  - Exploit as much problem structure as you can
  - Use strong formulations; when in doubt, add more constraints
  - Help the solver with cutoff values and branch priorities
  - First get a feasible answer, then work from there
- Once you're feasible, work on improvement
  - Throw more switches to drive down the integrality gap
  - Recognize that some problems have "loose" LP formulations and require very long b-b solves to tighten the gap
  - Pay close attention to the structure of the interim feasible solutions
  - Add more constraints if you see opportunities (like the NOSWOT problem)

# **Constraint-Satisfaction Problems (CSPs)**

- Sometimes we just want to find a *feasible* solution
- Map-coloring problem:
  - assign colors to maps so no adjacent countries have the same color
- Stable marriage problem
  - Have a group of N men, and a group of N women
  - Each woman has rated the men 1-N, as have each of the men
  - Assign men to the women so that if Man A prefers Man B's wife, Man B's wife prefers her husband to Man A
- Scene labeling
  - Recognize 3-D objects by assigning lines in 2-D drawings

## The Idea of Constraint Programming

#### Basic algorithm

- You have a set of variables, each with a finite domain
- You have a set of constraints that determine allowable settings on combinations of variables
- Successive applications of those constraints reduce the domains of the variables
- Stop when you come up with variable settings that satisfy all constraints
- Several commercial products, such as ILOG's OPL, provide a language for constraint programming

## **Integer Programming for CSPs**

- In some cases, we can write integer programs to solve CSPs
- Consider SuDoKu
  - Problems consist of a 9 x 9 grid
  - Have to assign numbers 1-9 so that each row, column, and the 93 x 3 subgrids contains each number exactly once
- How do you solve these manually?
- Chances are, you use your own version of constraint programming

## **The Challenge**

- Formulate an integer program in MPL to solve the SuDoKu problem shown to the right
- Furthermore, SuDoKu puzzles are advertised to have a *single* solution
- Does this one have a single solution? Modify your formulation to find out

| 7 |   | 3 |   | 1 |   |   |   |   |
|---|---|---|---|---|---|---|---|---|
|   | 6 |   | 8 | 4 |   | 3 |   |   |
|   |   | 5 |   |   |   |   | 8 |   |
|   |   |   |   |   |   | 2 |   | 8 |
|   | 2 |   | 1 |   |   |   | 6 |   |
| 6 |   | 9 |   |   |   |   |   |   |
|   | 5 |   |   |   |   | 1 |   |   |
|   |   | 6 |   | 3 | 5 |   | 4 |   |
|   |   |   |   | 2 |   | 7 |   | 9 |