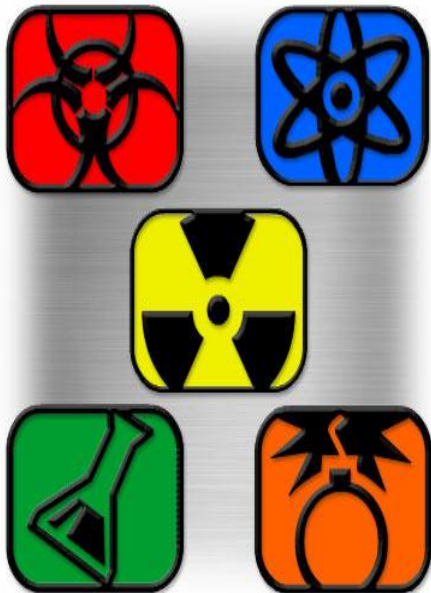


Ubiquitous (CB)RN(E) Sensor Networks: An Analysis of Parameters Final Report



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Agenda

- Introduction
- Problem Statement
- Scenario
- Assumptions
- Modeling
 - Sensor Generation
 - Main Loop
 - Localization
- Variables
- Analysis
 - Metrics
 - Results
- Framework
- Closure
- Questions

Introduction

- TASC Inc.
 - Protect US from harmful materials
- CBRNE devices pose a threat to major public events across the country:
 - Recent plots: Boston Marathon Bombing, New York City Subway plot



Problem Statement

- Determine metrics for a comparison of the effectiveness of different networks containing varying parameters.
- Determine any relationships existing between (CB)RN(E) source strength, network density, and sensor strength and subsequently, their impact on interdiction.
- Introduce a framework for a ubiquitous sensor network that localizes a (CB)RN(E) source prior to its detonation or release.

Scenario

- Macy's Thanksgiving Day Parade
 - Central Park West from 75th Avenue to 74th Avenue
 - Radioactive / Nuclear Source moving through crowd



Assumptions

- Personal privacy legality is a non-issue
- Sensor implementation is feasible
- Agnostic Sensor/Source
 - Radioactive/Nuclear type emanation
- One sensor per person/parade participant
 - Source does not have a sensor
- No weather effects on sensor detection or source emanation
- One source
 - False detections will be analyzed, but not false targets (multi-target)
 - Entry point/drop off location are fixed for all runs

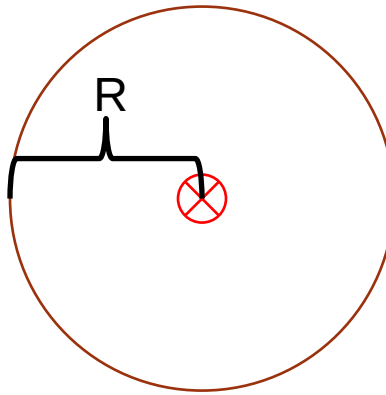
Variables

- Base Case
 - Crowd Density
 - Sensor Strength
 - Source Strength
- Excursion - Movement
 - Source
 - Randomness
 - Crowd
 - Individual Chance
 - Parade
- Excursions - Degradation
 - Minimum Sensor Efficiency
 - False Detection
 - Recur Rate
 - Attenuation
 - Range
 - Number of Sensors
 - Negative Detection
 - Recur Rate

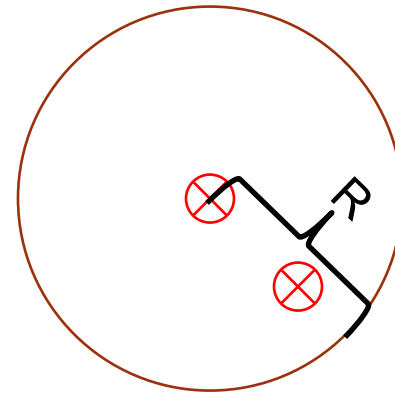
Variables- Important Definitions

- False Detections
 - Recur Rate
 - Attenuation Range
 - Attenuation Number
- Negative Detections
 - Recur Rate

Attenuation: Range - R, Number - 2



Detection Not Used



Detection Used

"See Distance"

- Largest distance at which a sensor can detect the source
- Distance from source to sensor must be less than or equal to the "See Distance" for a detection to occur

	2.0	1.41	2.00	2.45	2.83	3.16	3.46	3.74	4.00	4.24	4.47	4.69	4.90	5.10	5.29	5.48	5.66	5.83	6.00	6.16	6.32
	1.9	1.38	1.95	2.39	2.76	3.08	3.38	3.65	3.90	4.14	4.36	4.57	4.77	4.97	5.16	5.34	5.51	5.68	5.85	6.01	6.16
	1.8	1.34	1.90	2.32	2.68	3.00	3.29	3.55	3.79	4.02	4.24	4.45	4.65	4.84	5.02	5.20	5.37	5.53	5.69	5.85	6.00
	1.7	1.30	1.84	2.26	2.61	2.92	3.19	3.45	3.69	3.91	4.12	4.32	4.52	4.70	4.88	5.05	5.22	5.38	5.53	5.68	5.83
	1.6	1.26	1.79	2.19	2.53	2.83	3.10	3.35	3.58	3.79	4.00	4.20	4.38	4.56	4.73	4.90	5.06	5.22	5.37	5.51	5.66
	1.5	1.22	1.73	2.12	2.45	2.74	3.00	3.24	3.46	3.67	3.87	4.06	4.24	4.42	4.58	4.74	4.90	5.05	5.20	5.34	5.48
	1.4	1.18	1.67	2.05	2.37	2.65	2.90	3.13	3.35	3.55	3.74	3.92	4.10	4.27	4.43	4.58	4.73	4.88	5.02	5.16	5.29
	1.3	1.14	1.61	1.97	2.28	2.55	2.79	3.02	3.22	3.42	3.61	3.78	3.95	4.11	4.27	4.42	4.56	4.70	4.84	4.97	5.10
	1.2	1.10	1.55	1.90	2.19	2.45	2.68	2.90	3.10	3.29	3.46	3.63	3.79	3.95	4.10	4.24	4.38	4.52	4.65	4.77	4.90
	1.1	1.05	1.48	1.82	2.10	2.35	2.57	2.77	2.97	3.15	3.32	3.48	3.63	3.78	3.92	4.06	4.20	4.32	4.45	4.57	4.69
	1.0	1.00	1.41	1.73	2.00	2.24	2.45	2.65	2.83	3.00	3.16	3.32	3.46	3.61	3.74	3.87	4.00	4.12	4.24	4.36	4.47
	0.9	0.95	1.34	1.64	1.90	2.12	2.32	2.51	2.68	2.85	3.00	3.15	3.29	3.42	3.55	3.67	3.79	3.91	4.02	4.14	4.24
	0.8	0.89	1.26	1.55	1.79	2.00	2.19	2.37	2.53	2.68	2.83	2.97	3.10	3.22	3.35	3.46	3.58	3.69	3.79	3.90	4.00
	0.7	0.84	1.18	1.45	1.67	1.87	2.05	2.21	2.37	2.51	2.65	2.77	2.90	3.02	3.13	3.24	3.35	3.45	3.55	3.65	3.74
	0.6	0.77	1.10	1.34	1.55	1.73	1.90	2.05	2.19	2.32	2.45	2.57	2.68	2.79	2.90	3.00	3.10	3.19	3.29	3.38	3.46
	0.5	0.71	1.00	1.22	1.41	1.58	1.73	1.87	2.00	2.12	2.24	2.35	2.45	2.55	2.65	2.74	2.83	2.92	3.00	3.08	3.16
	0.4	0.63	0.89	1.10	1.26	1.41	1.55	1.67	1.79	1.90	2.00	2.10	2.19	2.28	2.37	2.45	2.53	2.61	2.68	2.76	2.83
	0.3	0.55	0.77	0.95	1.10	1.22	1.34	1.45	1.55	1.64	1.73	1.82	1.90	1.97	2.05	2.12	2.19	2.26	2.32	2.39	2.45
	0.2	0.45	0.63	0.77	0.89	1.00	1.10	1.18	1.26	1.34	1.41	1.48	1.55	1.61	1.67	1.73	1.79	1.84	1.90	1.95	2.00
	0.1	0.32	0.45	0.55	0.63	0.71	0.77	0.84	0.89	0.95	1.00	1.05	1.10	1.14	1.18	1.22	1.26	1.30	1.34	1.38	1.41
		1.0	2.0	3.0	4.0	5.0	6.0	7.0	8.0	9.0	10.0	11.0	12.0	13.0	14.0	15.0	16.0	17.0	18.0	19.0	20.0

Source/Sensor → See Distance
 1.8/5.0 1.5/6.0 1.0/9.0 → 3.00

$$\text{Max See Distance} = \sqrt{\text{sensor strength} * \text{source strength}}$$

Model - Input

Status: Runs complete.

Main Variables

What Density do you want (people/m²)?
Source Strength
Sensor Strength
Max See Distance

Single Variable	Multiple Variable Run		
	Start	End	Steps
0.25	0.25	7.00	11.00
7.00	0.50	7.00	7.00
0.14	0.14	7.00	7.00

Note

Between 0.1 & 7.0
Give a range
Give a range

Clear Output

Clear Visuals

Clear GIS & LL

Clear all Data

Movement

Randomness of Source Movement
Source avoids crowd
Persistence
Turn Crowd Movement on
Chance for each individual to move
Chance of Crowd Member Leaving
Parade Movement

Value	Range
0	From 0 to 100%
0	1-Yes, 0-No
0	Positive Integer
0	1-Yes, 0-No
0	From 0 to 100%
0	From 0 to 100%
0	1-Yes, 0-No

Data Writing

Write data for 'Visuals' Tab
Write GIS data

0	1-Yes 0-No
0	1-Yes 0-No

System Degradation

Minimum Sensor Efficiency
False Detection
False Detection Chance
Negative Detection
Negative Detection Chance
Attenuation
Range

100	From 0 to 100%
0	From 0 to 100%
5	From 0 to 100%
0	From 0 to 100%
0	From 0 to 100%
0	2-3 as starting value
9	5 as starting value

Values

Data Sets	5
Runs:	200
Time:	0:00:11
Not Seen:	133
Total Steps:	165
% Time Seen:	19%
Avg Detects for Est. Pos.	1.1
Min Error:	0.000
Average Error:	0.74
Max Error:	1.00
Last Position Error:	7.52
Max Location Error:	32.14
Confidence Level:	95%

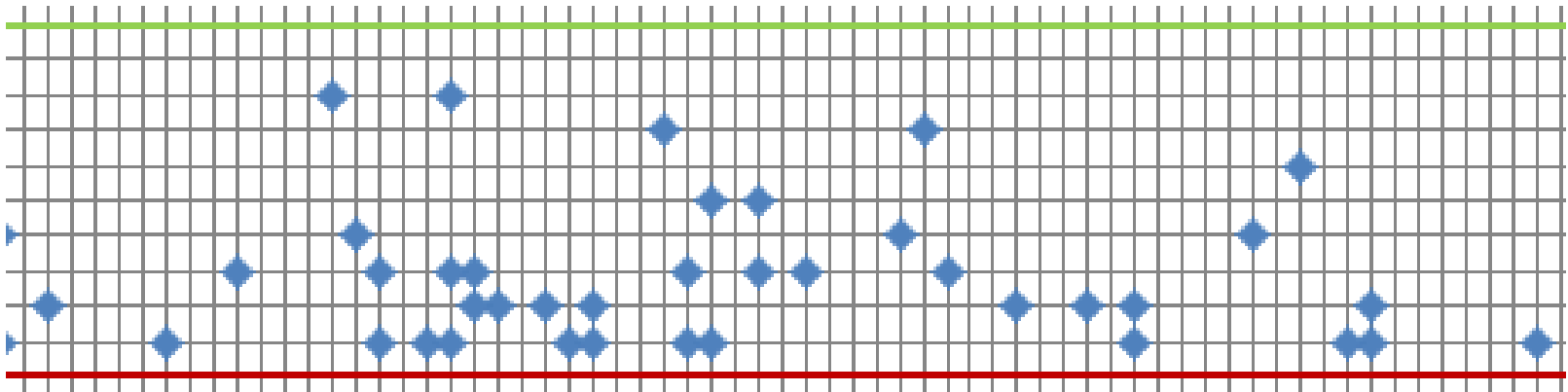
This data column is average values for multiple run data sets.

Model – Sensor Generation

- Sensor Generation (Parade Participants and Crowd)
 - Crowd
 - Randomly Generated using Uniform x-coordinate and Geometric y-coordinate
 - Density
 - Sensor Efficiency
 - False/Negative Detection Status
 - Parade
 - Set starting position
 - Sensor Efficiency
 - False/Negative Detection Status

Model Grid

- Max Density = 8 people per meter squared
- Grid unit = $1/\sqrt{8}$ meters (approximately 1.15 ft)



Model – Main Loop

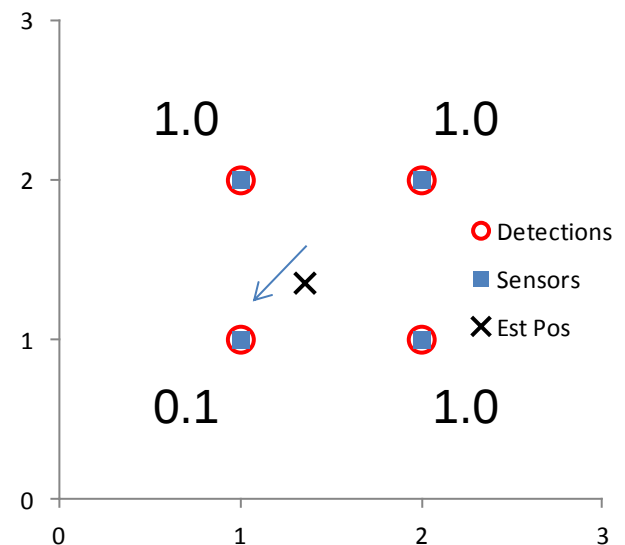
- Following events occur until Source reaches drop off location
 - Source Movement
 - Parade Movement
 - Crowd Movement
 - Detections – Parade/Crowd
 - Source Position Estimated
 - Metric Calculations

Source Localization

- Center of Mass calculation
- Sensor efficiency 0-100%
 - Efficiency: percentage of designed sensor strength
- “Mass” = 100/sensor efficiency
- Pulls the source closer to sensors with low efficiencies

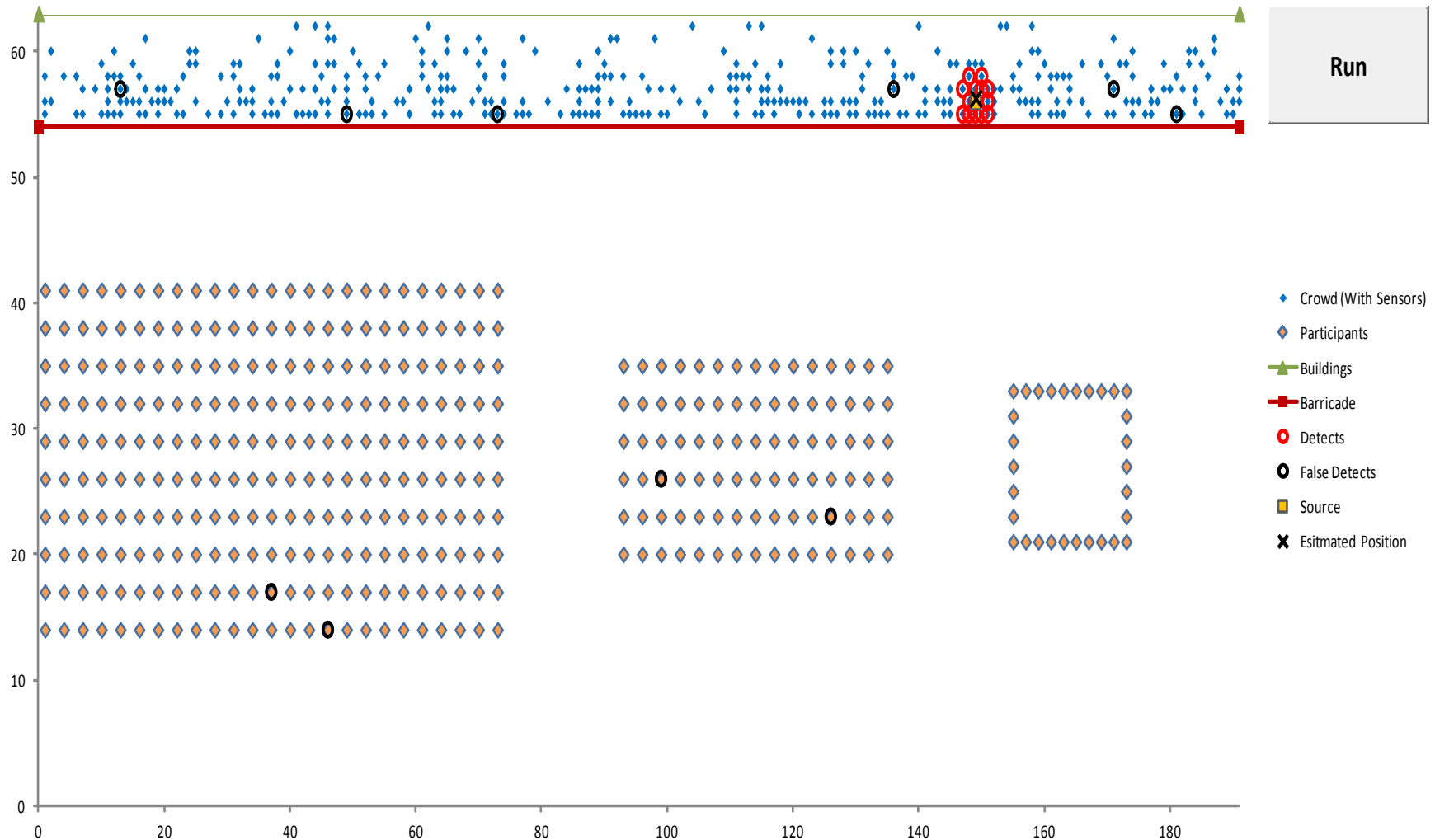
$$Est. x = \frac{1}{\sum_{i=1}^n \left(\frac{100}{Eff[i] * Str[i]} \right)} \sum_{i=1}^n x_i \left(\frac{100}{Eff[i] * Str[i]} \right)$$

$$Est. y = \frac{1}{\sum_{i=1}^n \left(\frac{100}{Eff[i] * Str[i]} \right)} \sum_{i=1}^n y_i \left(\frac{100}{Eff[i] * Str[i]} \right)$$

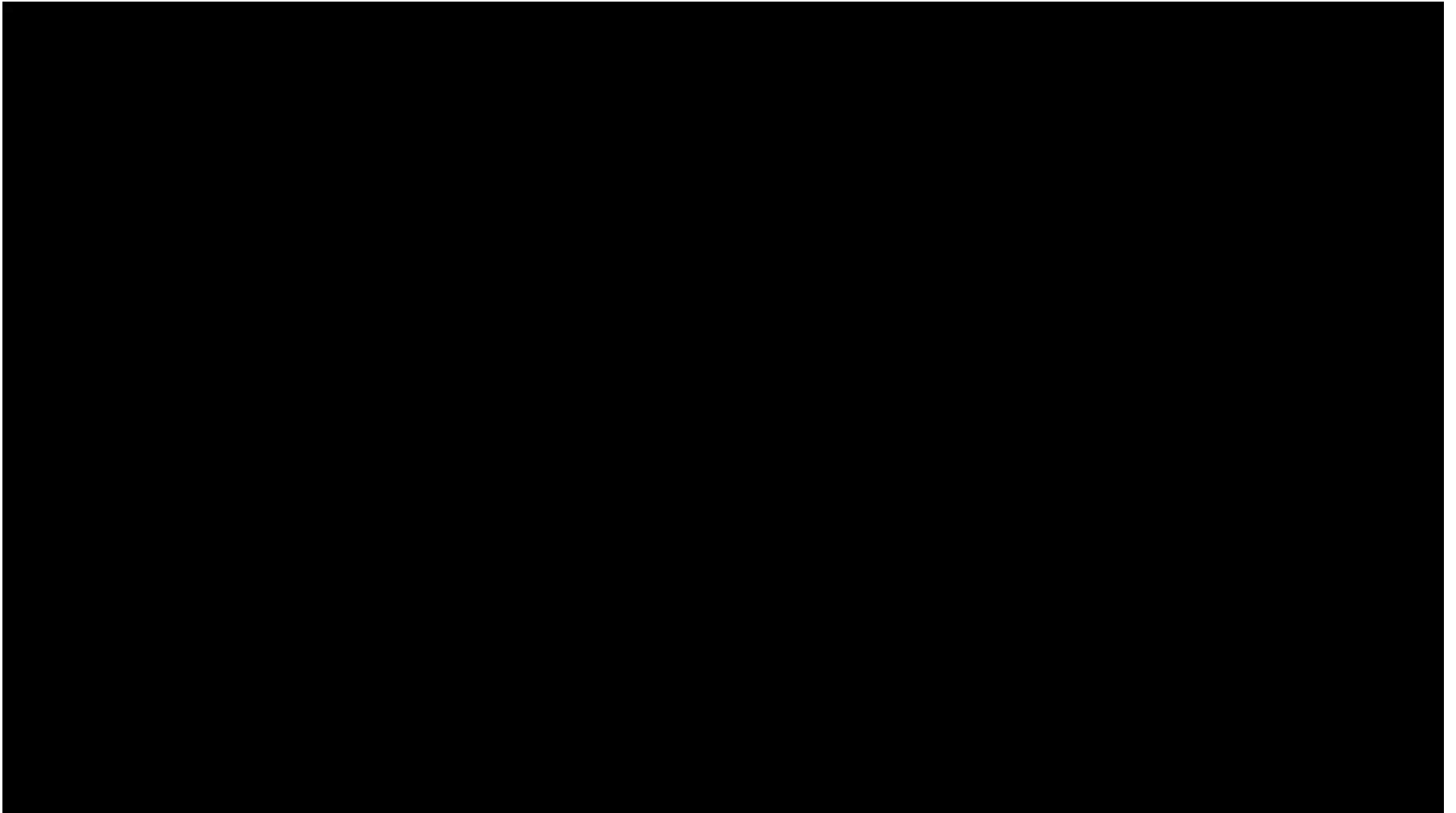


Model - Verification

Not Seen: 8 Total Steps: 41 Time Seen: 80% Avg Detects for Est. Pos.: 6.2 Min Error: 0.143 Average Error: 4.82 Max Error: 134.02 Last Position Error: 0.26 Max Location Error: 134.0203



GIS Model: Video



Metrics

- Percent of Time Source is Seen
- Average Error When Source Seen
- Max Error When Source Seen
- Last Estimated Position
- Max Location Error

	Values
Data Sets	5
Runs	200
Time	0:00:11
Not Seen	133
Total Steps	165
% Time Seen	19%
Avg Detects for Est. Pos.	1.1
Min Error	0.000
Average Error	0.74
Max Error	1.00
Last Position Error	7.52
Max Location Error	32.14
Confidence Level	95%

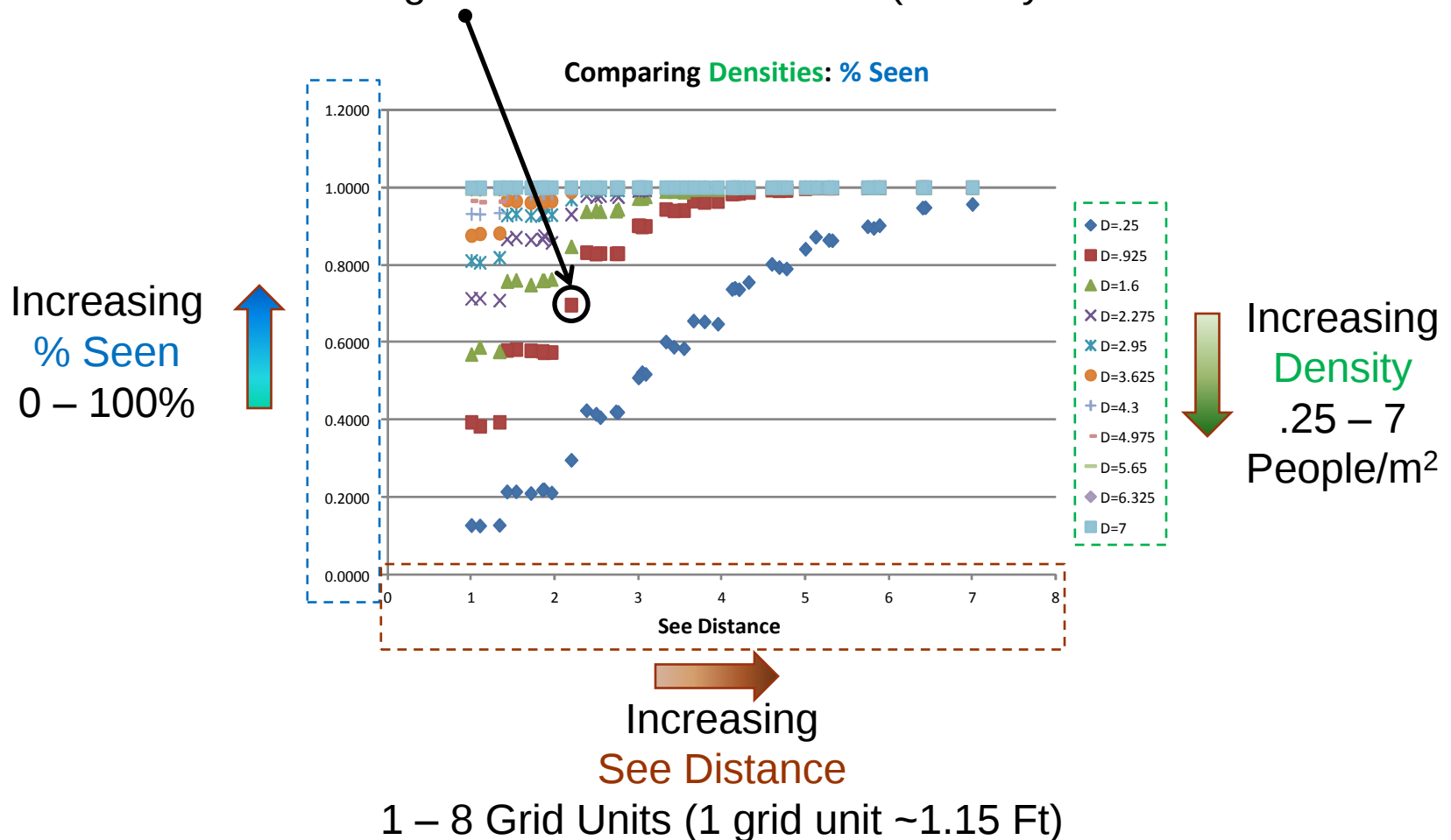
This data column is
average values for
multiple run data sets.

Analysis

- Base Case
 - Vary Density, Source Strength, Sensor Strength
 - Source Only Movement (Non Random)
 - All Sensors 100% Effective
 - No False/Negative Detections
- Excursions
 - Random Source Movement
 - Crowd/Parade Movement
 - Negative Detects
 - False Detects (Attenuation Parameters)
 - Various Distributions for Sensor Efficiencies

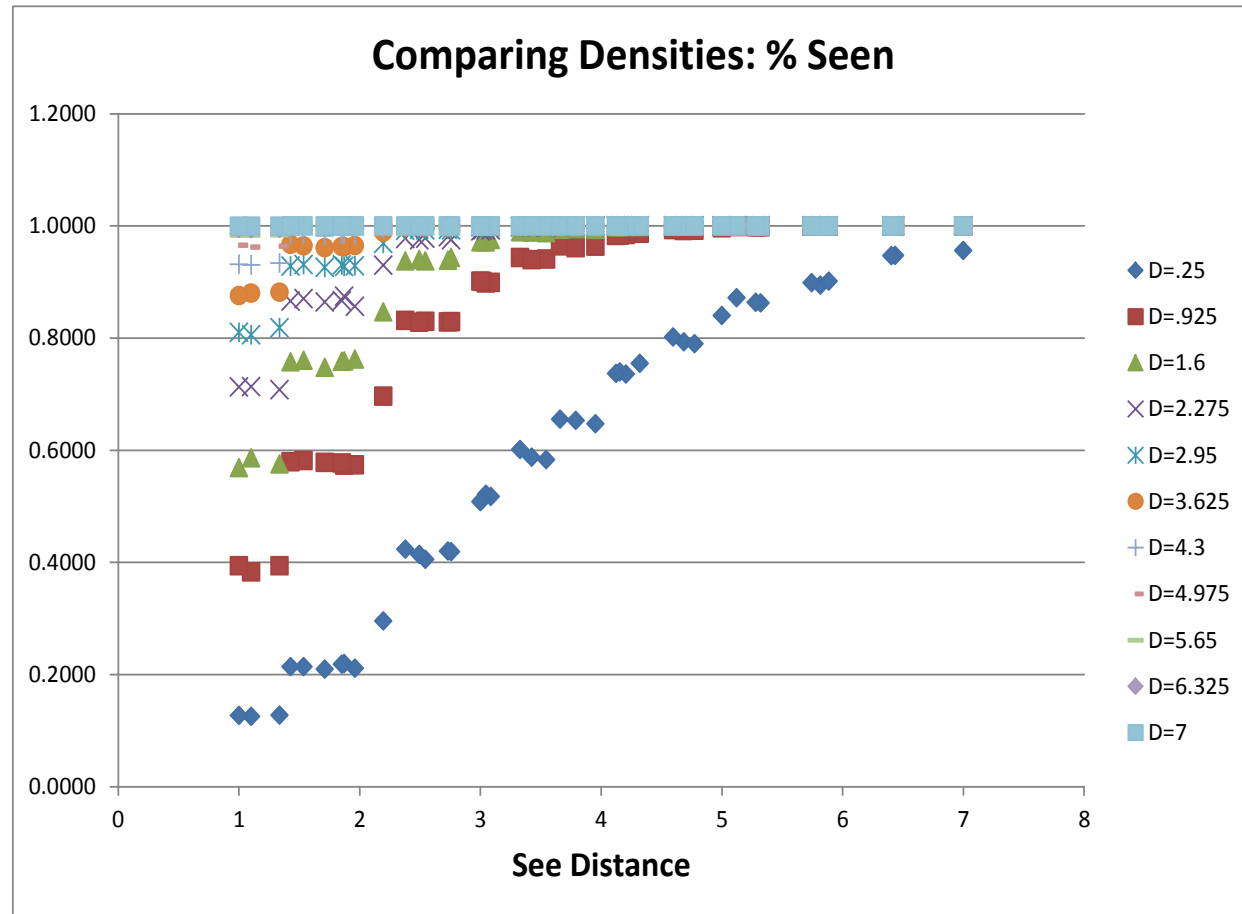
Analysis – Data Slides

Each Data Point – Average of 200 Individual Runs (Density = .925 See Distance = 2.2)



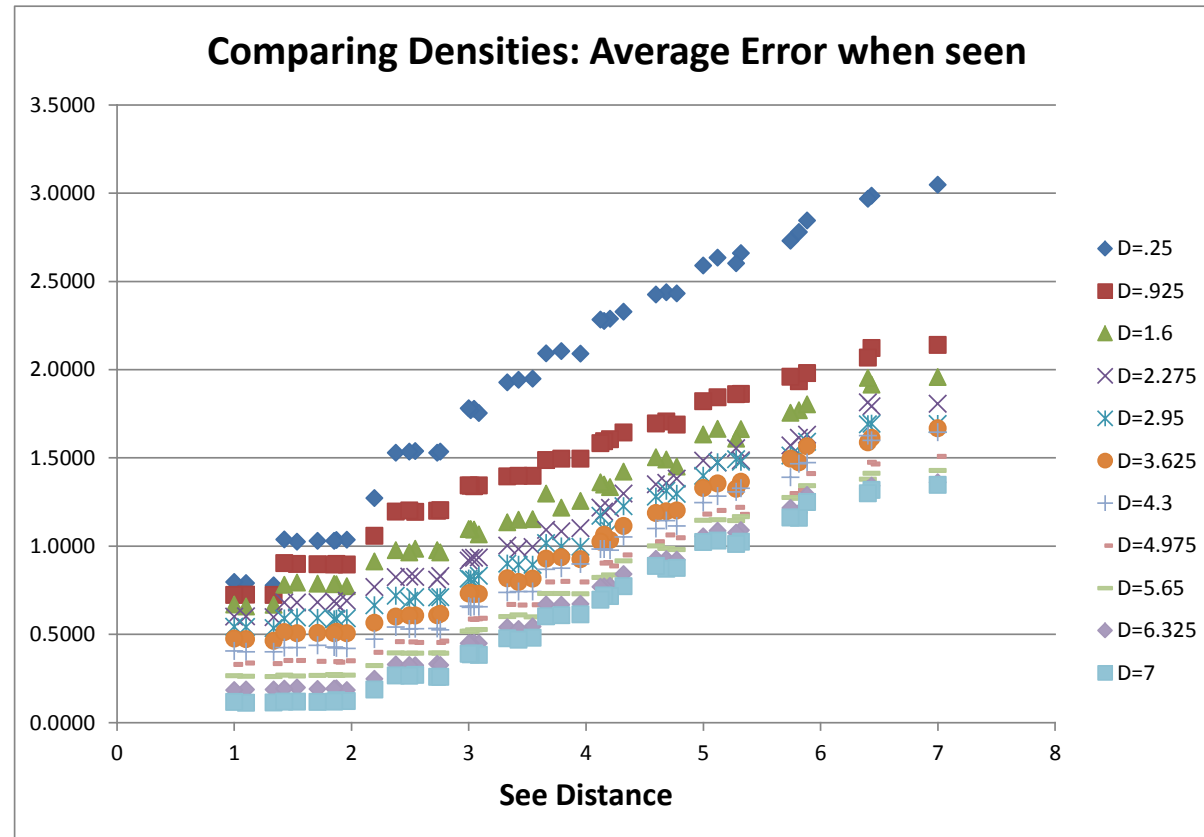
Base Case Analysis- Percent Seen

- As density increases, the percent of the time the source is seen increases
- As “see distance” increases, the percent of the time the source is seen increases



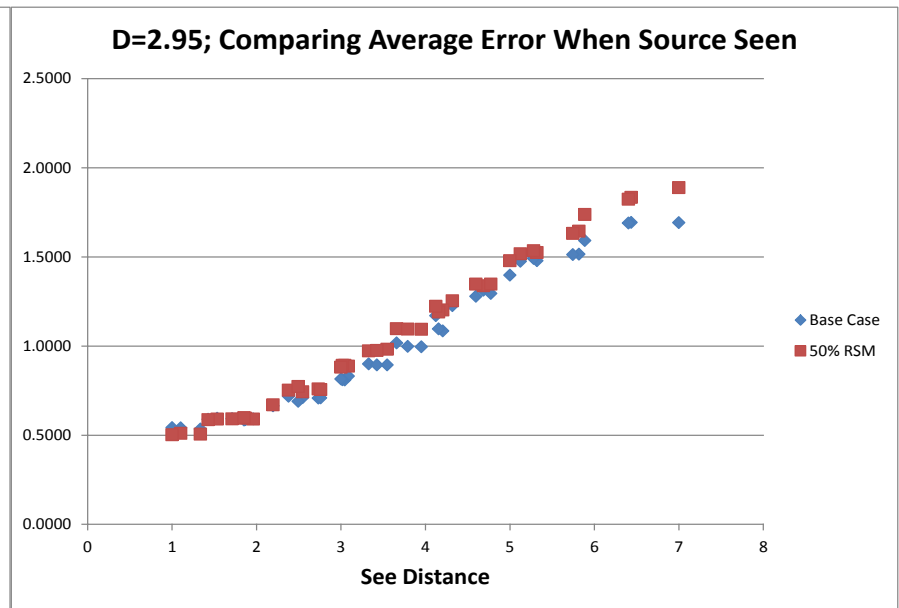
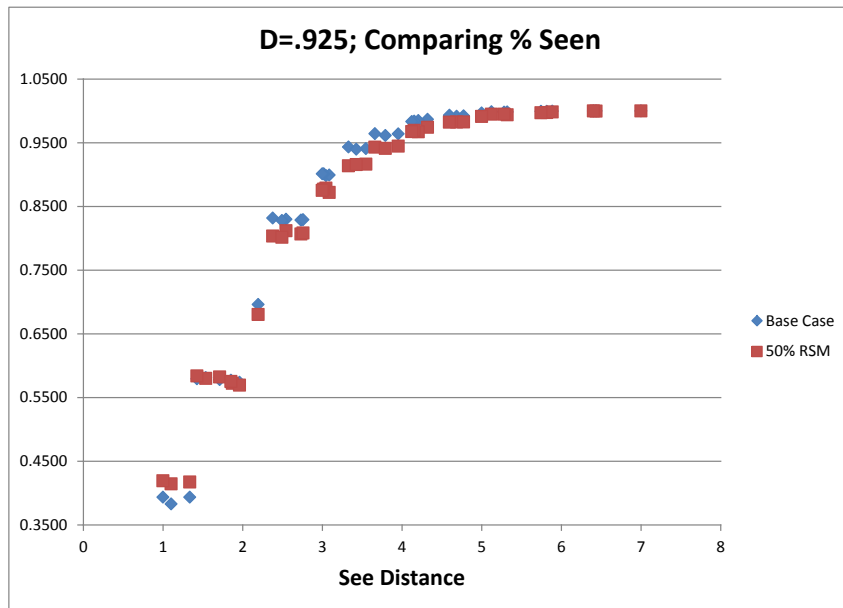
Base Case Analysis- Average Error When Seen

- As density increases, the average error when the source is seen decreases
- As “see distance” increases, the average error when the source is seen increases



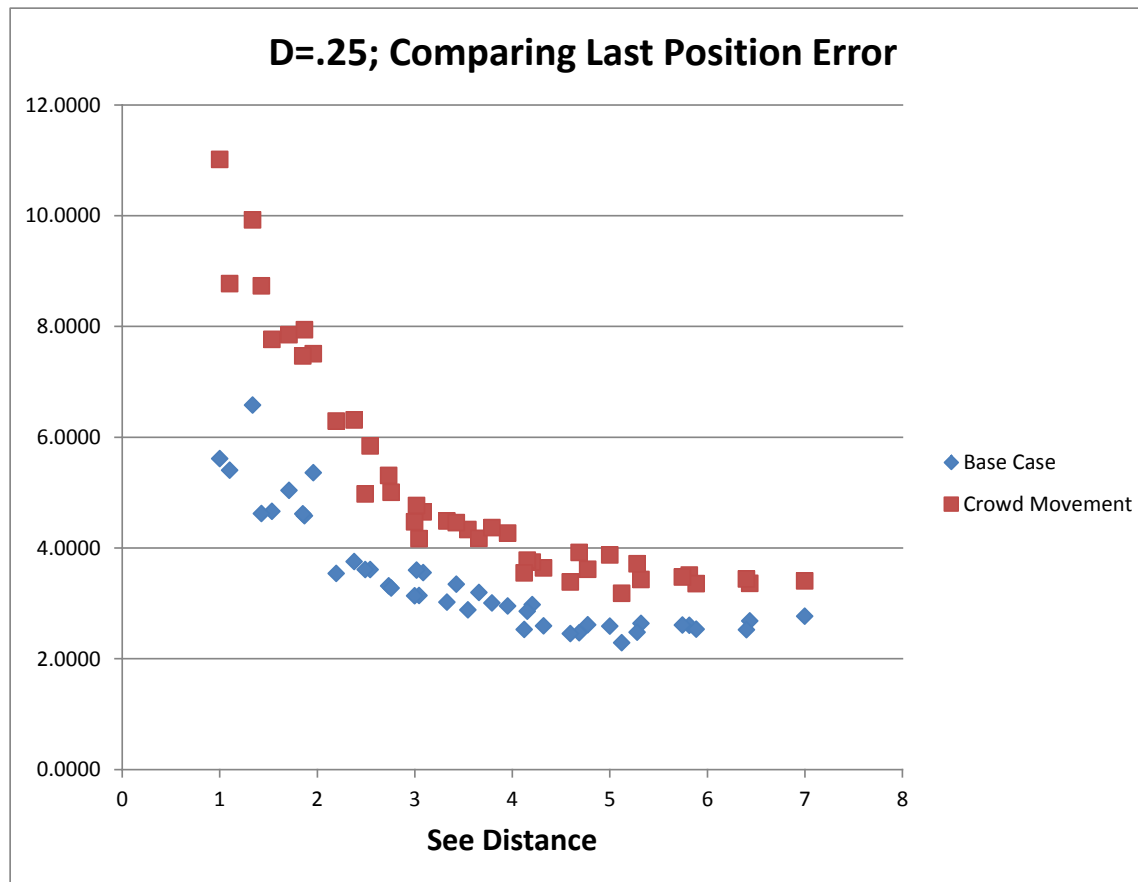
Excursion Analysis: Random Source Movement

- Little to no variation from the base case for all metrics



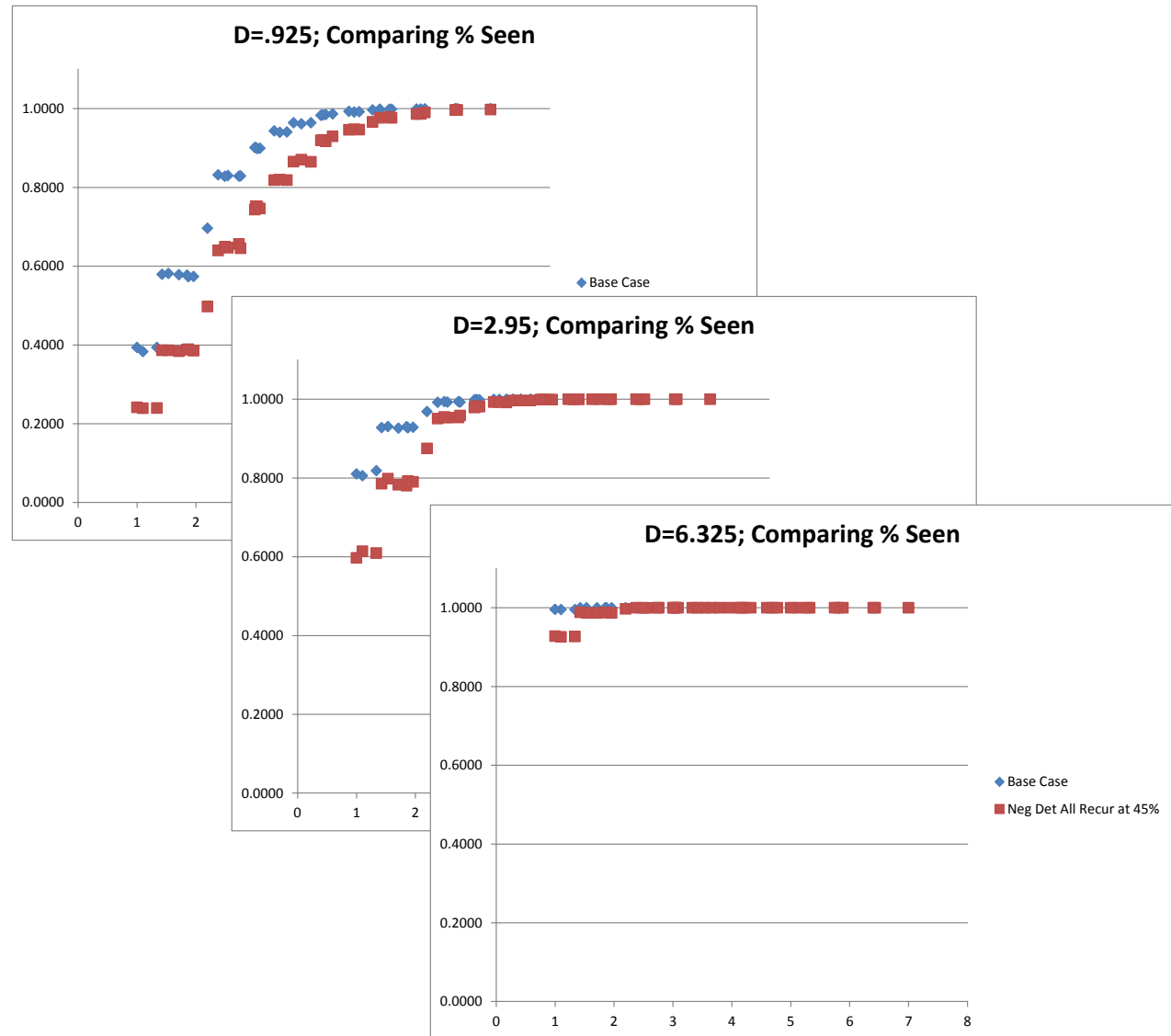
Excursion Analysis- Crowd Movement

- Minor effect on percent seen
- Significant effect on last position error

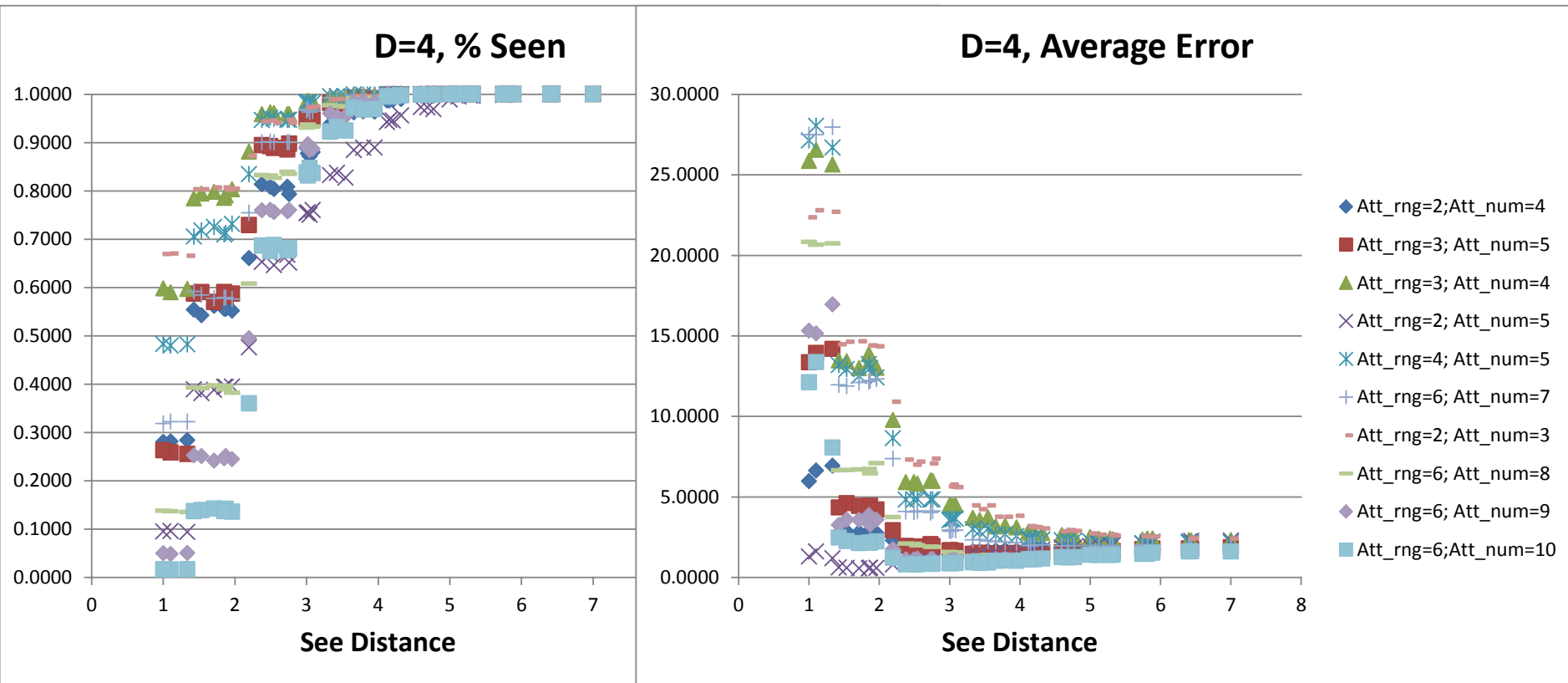


Excursion Analysis-Negative Detections

- 5% recurrence: no significant effect
- 25% and 45% recurrence: percent seen and maximum location error are affected.
- These effects occur at low densities and/or low “see distances”



Excursion Analysis-False Detects



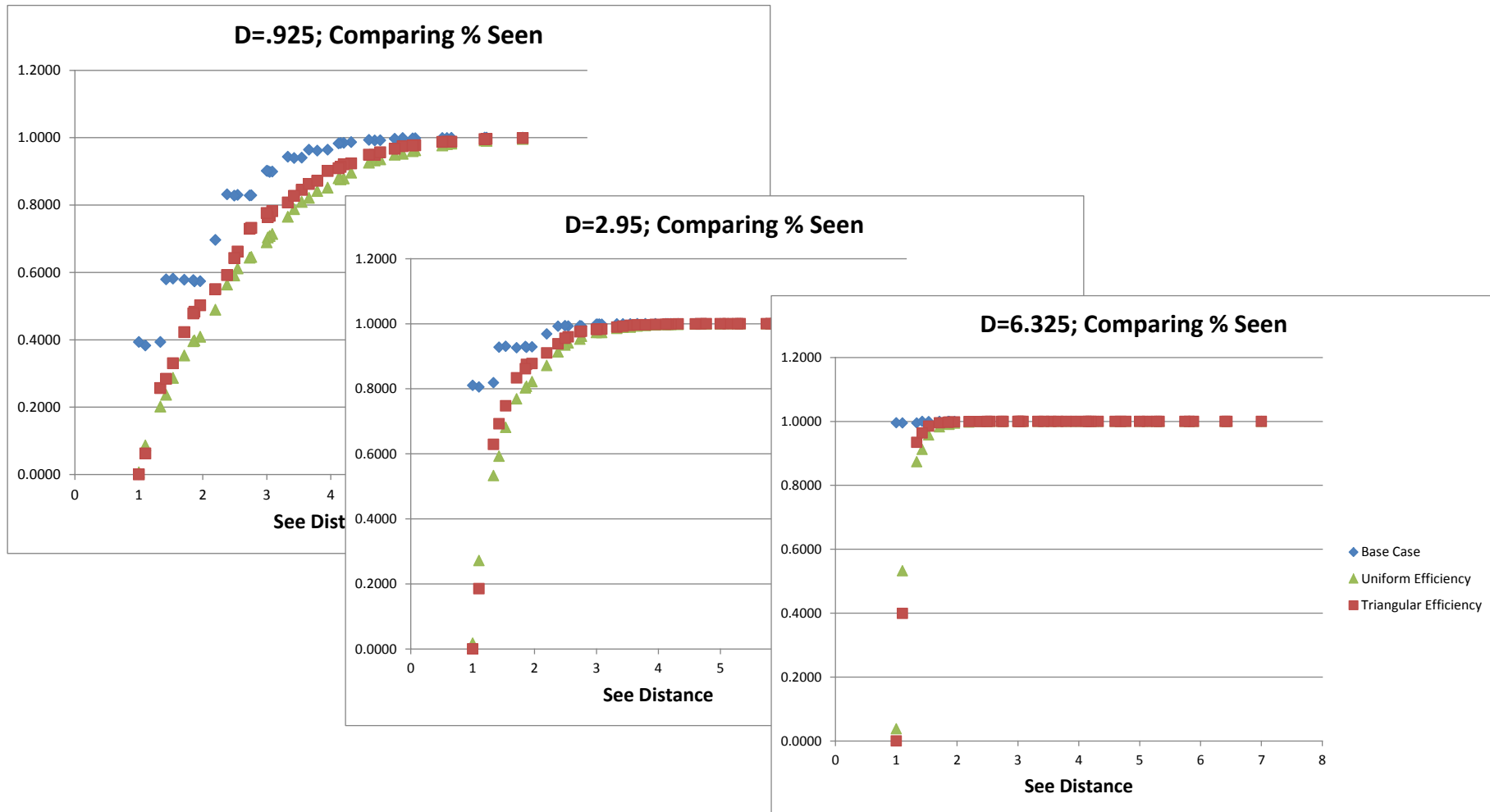
Excursion Analysis-Distribution of Efficiencies

- Little difference between Uniform[0,100] and Triangular[0,75,100]
- “See distances” in the interval [2, 4] give the most effective network
 - The higher the density, a lower “see distance” is desired to give a better average error
 - The lower the density, a higher “see distance” is desired to give a better percent seen

A balance is needed for an effective network

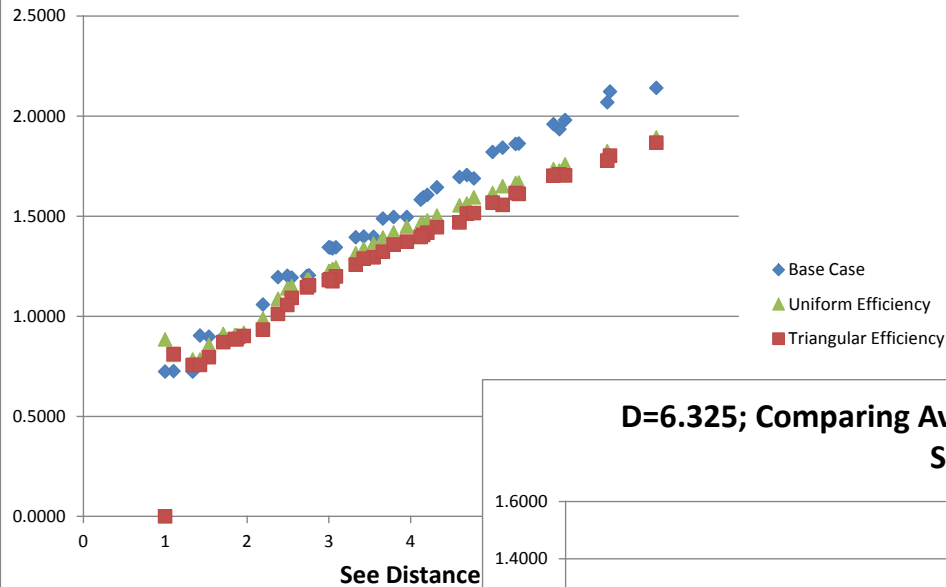
Excursion Analysis-Distribution of Efficiencies (Percent Seen)

- Major effect at low densities and/or low see distances

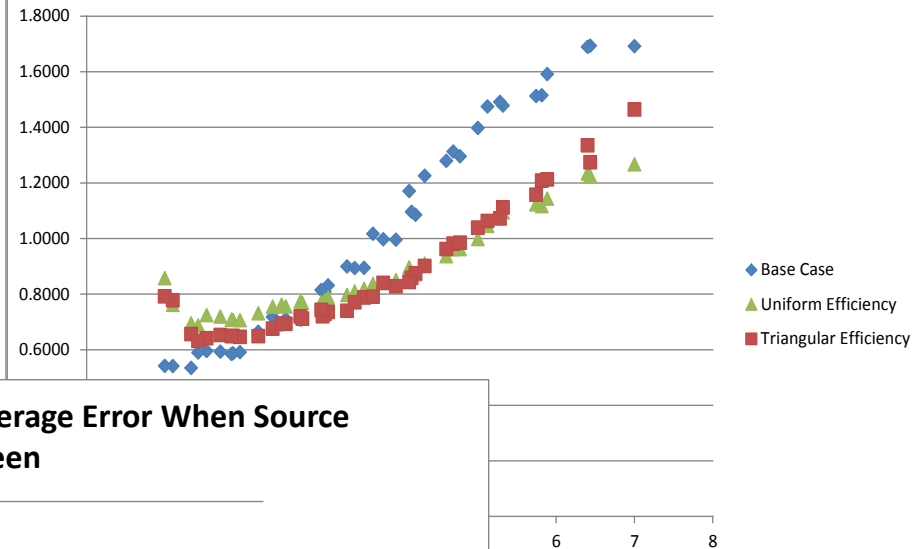


Excursion Analysis-Distribution of Efficiencies (Average Error)

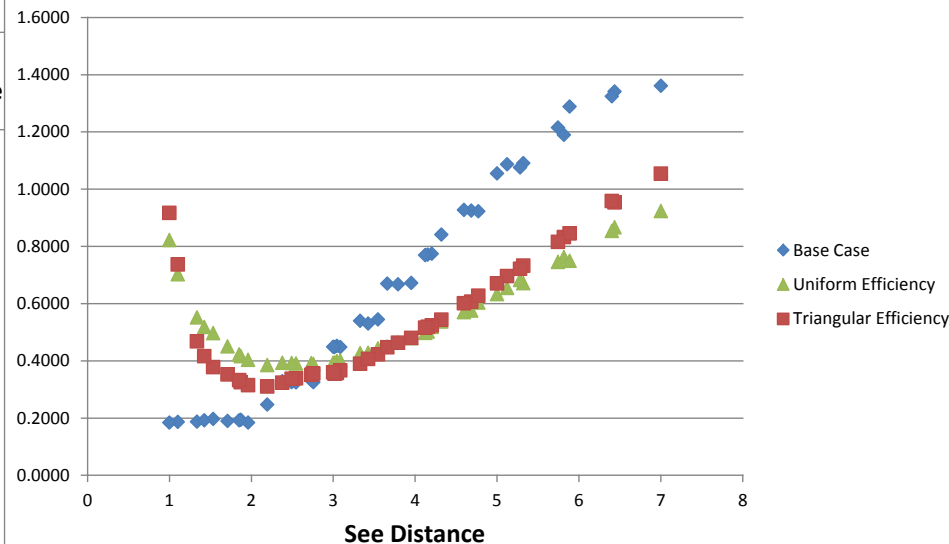
D=.925; Comparing Average Error When Source Seen



D=2.95; Comparing Average Error When Source Seen



D=6.325; Comparing Average Error When Source Seen



Conclusions :

Framework Characteristics I

- **An estimated strength of a source determines the required sensor strength**
- **Beneficial Sensor Characteristics**
 - A strong sensor that can be dampened
 - Higher density network – lower sensor strength
 - Lower density network – higher sensor strength
 - A sensor able to detect levels of source emanation
 - Strong sensor

Conclusions :

Framework Characteristics II

- **Negative Detections**

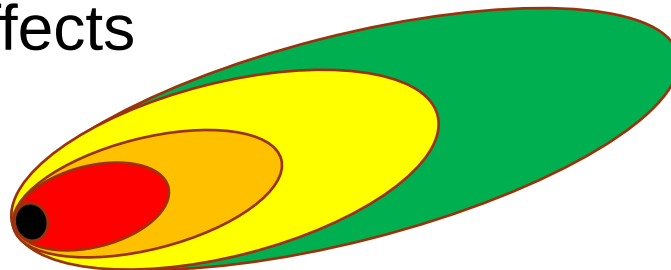
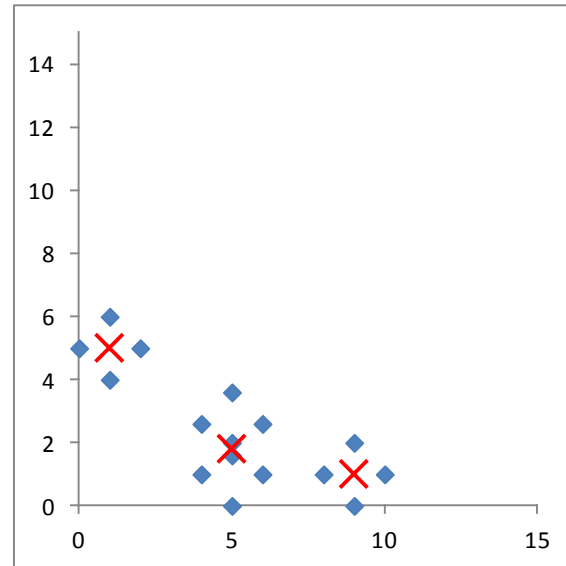
- Limit the percentage chance of a negative detection
- High sensor strength/network density can minimize the effects of negative detections

- **False Detections**

- Use an attenuation parameter
- Non-detect mode
- Other localization methods (time-based) and multi targeting algorithms are significant for providing better source position estimation

Recommendations

- **Multiple target tracking**
 - Multiple Sources
 - False Targets
- **Time based tracking**
 - Target Prediction
 - False Target Elimination
- **Fluid type dispersion**
 - Chemical, Biological, Explosive Source
 - Weather Effects



Thank You

- Allen Harvey, TASC, Inc.
- Lorton Team, TASC, Inc.
- Dr. Laskey, Capstone Instructor
- George Mason Faculty

Backup Slides

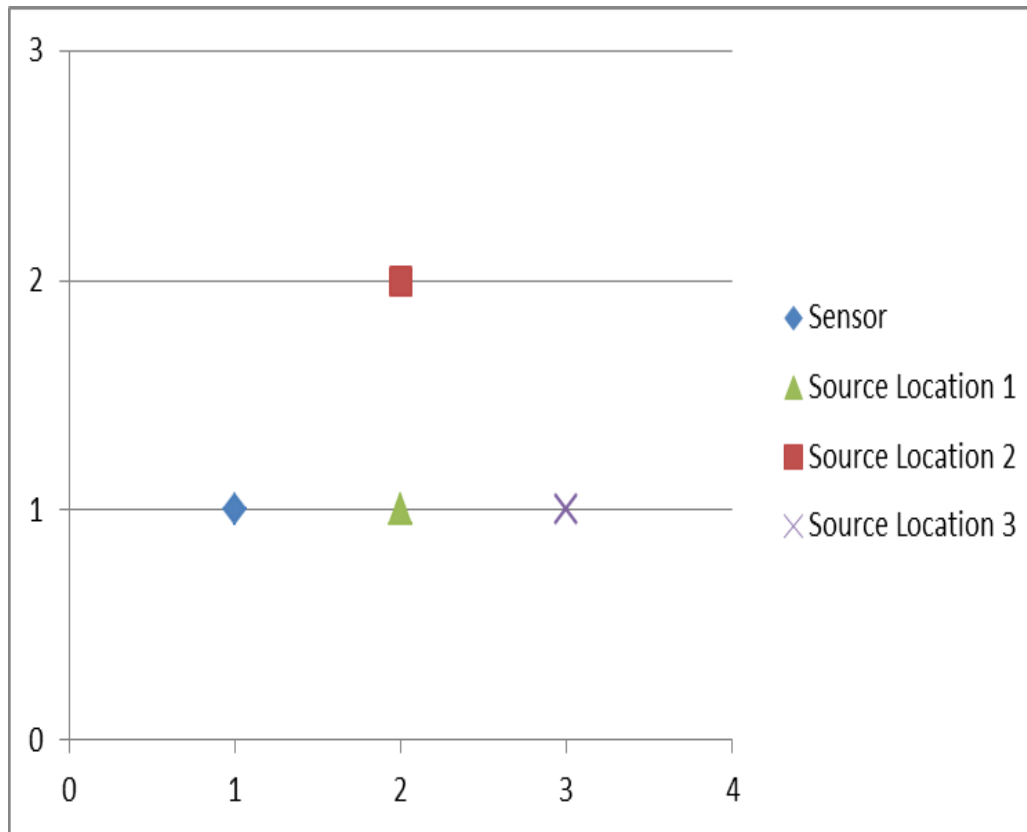
Deriving “See Distance”

- A sensor strength of S_e has the ability to see $\frac{1}{S_e} \frac{\text{source units}}{\text{grid units}^2}$
- Source degrades using $\frac{S_o}{R^2}$
- For a detection:
 - $\frac{S_o}{R^2} \geq \frac{1}{S_e}$
 - $R \leq \sqrt{S_o * S_e}$
- R =distance from source to sensor
- S_o = Source strength
- S_e = Sensor strength

Reason For Data Clusters

• Detection if:

- Distance from S_o to $S_e \leq \sqrt{S_o \text{ Strength} * S_e \text{ Strength}}$



Model - Output

42,000	Input																				Output																		
	Main Variables			Movement						Visuals		System Degradation						#Runs	CL	Steps						Error													
																				Avg Detects for Est. Pos.						Error													
Data Set #	Density	Source Str	Sensor Str	So Rnd	So Avoid	So Persist	Crowd Move	Crowd %	Crowd Leave	Parade	Vis	GIS	Min Sensor Eff	False Detect	False %	Neg Detect	Neg %	Att. Number	Att. Dist.	#Runs	CL	Steps Not Seen	HW	Steps	HW	% Seen	HW	HW	Min Error	HW	Avg Error	HW	Max Error	HW	Last Position Error	HW	Max Location Error	HW	
1.000	0.2500	0.5000	2.4286	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	142.0600	0.6959	165.0000	0.0000	0.1390	0.0042	2.2013	0.0167	1.4450	0.3333	51.8647	1.3207	142.0891	2.6705	59.6061	7.4702	143.6606	2.5416
2.000	0.2500	0.5000	3.5714	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	142.5000	0.6670	165.0000	0.0000	0.1364	0.0040	2.1842	0.0166	1.2583	0.3920	51.1133	1.5791	140.7740	3.2851	60.9100	7.3249	142.5349	3.1239
3.000	0.2500	0.5000	4.7143	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	138.7650	0.8062	165.0000	0.0000	0.1590	0.0049	2.2354	0.0196	0.5041	0.0858	43.1811	1.3905	138.6480	3.0447	54.5834	7.3038	140.4886	2.8988
4.000	0.2500	0.5000	5.8571	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	139.1750	0.8216	165.0000	0.0000	0.1565	0.0050	2.2385	0.0193	0.4787	0.0838	43.5868	1.4228	141.8580	3.0189	54.0278	7.0604	143.0737	2.9469
5.000	0.2500	0.5000	7.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	138.9250	0.8685	165.0000	0.0000	0.1580	0.0053	2.2481	0.0203	0.5815	0.1426	44.4106	1.5167	141.2184	3.4523	50.1880	7.1765	142.5717	3.3586
6.000	0.2500	1.5833	1.2857	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	137.8750	0.8530	165.0000	0.0000	0.1644	0.0052	2.2405	0.0201	0.5004	0.0889	41.8490	1.4710	138.9752	3.0734	50.6231	7.2352	140.3935	2.9327
7.000	0.2500	1.5833	2.4286	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	137.9500	0.8837	165.0000	0.0000	0.1639	0.0054	2.2396	0.0176	0.5000	0.0772	43.7362	1.5107	140.2378	3.0527	45.2850	6.9631	141.8053	2.9136
8.000	0.2500	1.5833	3.5714	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	124.8900	1.1284	165.0000	0.0000	0.2431	0.0068	2.3752	0.0221	0.2699	0.0406	29.8098	1.2966	141.0296	3.1052	43.6104	7.3073	142.3990	3.0031
9.000	0.2500	1.5833	4.7143	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	125.1550	1.2252	165.0000	0.0000	0.2415	0.0074	2.3694	0.0223	0.2952	0.0525	28.8536	1.3163	138.7061	3.0273	41.6658	7.0548	139.9898	2.9351
10.000	0.2500	1.5833	5.8571	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	115.0600	1.4958	165.0000	0.0000	0.3027	0.0091	2.4681	0.0223	0.2455	0.0371	23.2198	1.0681	141.6164	3.4177	31.1647	6.3383	142.4004	3.3546
11.000	0.2500	1.5833	7.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	105.1850	1.6108	165.0000	0.0000	0.3625	0.0098	2.5713	0.0248	0.2737	0.0384	19.1214	0.8705	137.9536	3.2341	31.2803	6.6671	139.2824	3.1310
12.000	0.2500	2.6667	1.2857	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	137.9750	0.8643	165.0000	0.0000	0.1638	0.0052	2.2344	0.0170	0.6627	0.3491	43.7567	1.5567	141.5294	2.8914	53.7748	7.2402	143.1249	2.7332
13.000	0.2500	2.6667	2.4286	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	126.3000	1.1531	165.0000	0.0000	0.2345	0.0070	2.3613	0.0214	0.2643	0.0403	28.5350	1.2333	138.2975	3.3834	34.1558	6.4961	139.6157	2.9232
14.000	0.2500	2.6667	3.5714	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	115.7050	1.3745	165.0000	0.0000	0.2988	0.0083	2.4650	0.0253	0.2473	0.0370	22.2092	1.0121	136.6682	3.2824	33.0460	6.0205	137.5945	3.2187
15.000	0.2500	2.6667	4.7143	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	107.2550	1.5061	165.0000	0.0000	0.3500	0.0091	2.5790	0.0279	0.2683	0.0338	19.2460	0.8088	138.8961	3.6666	31.9051	6.1862	139.5145	3.3666
16.000	0.2500	2.6667	5.8571	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	96.7550	1.6825	165.0000	0.0000	0.4136	0.0102	2.7118	0.0301	0.2680	0.0346	15.8343	0.8197	136.5925	3.7408	26.6887	5.7659	137.4122	3.6769
17.000	0.2500	2.6667	7.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	84.0500	1.8119	165.0000	0.0000	0.4906	0.0110	2.8627	0.0347	0.3118	0.0356	13.2953	0.5874	132.3623	3.4345	24.3040	5.5967	133.4202	3.3701
18.000	0.2500	3.7500	1.2857	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	134.1850	0.8727	165.0000	0.0000	0.1868	0.0053	2.2701	0.0191	0.3702	0.0558	39.0357	1.4942	142.2745	3.1960	46.2644	7.0460	143.7451	3.0497
19.000	0.2500	3.7500	2.4286	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	115.9200	1.3788	165.0000	0.0000	0.2975	0.0084	2.4799	0.0246	0.2664	0.0429	23.3187	1.0615	138.3270	3.1362	33.0065	6.4817	139.5460	3.0446
20.000	0.2500	3.7500	3.5714	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	96.7150	1.6204	165.0000	0.0000	0.4138	0.0098	2.6772	0.0270	0.2405	0.0359	16.1073	0.7801	136.6334	3.5467	30.1354	6.4777	137.9112	3.4233
21.000	0.2500	3.7500	4.7143	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	87.3050	1.8223	165.0000	0.0000	0.4709	0.0110	2.8041	0.0299	0.2935	0.0369	14.2225	0.6293	135.6566	3.6055	25.4132	5.7167	136.5310	3.5132
22.000	0.2500	3.7500	5.8571	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	76.2950	1.7812	165.0000	0.0000	0.5376	0.0108	2.9450	0.0324	0.2897	0.0364	12.2351	0.5468	133.3566	3.6397	28.2675	6.0150	134.5980	3.5828
23.000	0.2500	3.7500	7.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	100.0000	100.0000	5.0000	0.0000	0.0000	2.0000	6.0000	200.0000	0.9500	65.3100	1.6411	165.0000	0.0000	0.6042	0.0099	3.1440	0.0374	0.3295	0.0334	10.3141	0.4079	129.0644	4.1023	21.4842	5.2474	130.1319	4.0248
24.000	0.2500	4.8333	1.2857	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.																													

Model – GIS Data

61	56	1	14	47	56	74	58	49	58	49.7	56.8	61	56	1	14	47	56	106	57	48	58	48.2	56.6	61	56	1	14	47	56	4	55	47	58	46.8	56.7					
174	58	4	14	49	58	136	57					174	58	4	14	49	58	104	58					174	58	4	14	49	58	1	59									
47	56	7	14	45	57	3	58					47	56	7	14	45	57	15	57					47	56	7	14	45	57	58	20									
174	56	10	14	52	60	187	56					174	56	10	14	52	57	187	56					174	56	10	14	43	59	61	32									
22	60	13	14	53	57	103	55					22	60	13	14	51	58	129	59					22	60	13	14	51	58	105	35									
59	55	16	14	52	57	24	57					59	55	16	14	50	58	70	26					59	55	16	14	50	58	126	35									
141	56	19	14	53	59	34	35					141	56	19	14	51	56	43	32					141	56	19	14	48	55	161	21									
93	57	22	14	51	58	73	38					93	57	22	14	48	55	155	23					93	57	22	14	44	57	165	33									
145	55	25	14	50	58	155	23					145	55	25	14	44	57							145	55	25	14	43	58											
84	58	28	14	51	56							84	58	28	14	45	55							84	58	28	14	45	55											
49	58	31	14	48	55							49	58	31	14	49	56							49	58	31	14	44	55											
186	57	34	14	49	Crowd	Parade	True Detects				False Detects				Current				Estimated				Crowd	Parade	True Detects				False Detects				Current				Estimated			
106	60	37	14	50	40.77779	-73.975	40.77756	-73.9749	40.77775	-73.975	40.77783	-73.9749	40.77776	-73.975	40.77776	-73.975	40.77776	-73.975	40.77776	-73.975	40.77776	-73.975	40.77779	-73.975	40.77756	-73.9749	40.77775	-73.975	40.77772	-73.9749	40.77776	-73.975	40.77776	-73.975	40.77776	-73.975				
25	58	40	14	49	40.7781	-73.9747	40.77757	-73.9749	40.77776	-73.975	40.778	-73.9748										40.7781	-73.9747	40.77757	-73.9749	40.77776	-73.975	40.77791	-73.9749											
151	55	43	14	50	40.77775	-73.975	40.77758	-73.9749	40.77775	-73.975	40.77763	-73.9751										40.77775	-73.975	40.77758	-73.9749	40.77775	-73.975	40.77766	-73.9751											
97	55	46	14	46	40.7781	-73.9747	40.77759	-73.9749	40.77777	-73.975	40.77814	-73.9747										40.7781	-73.9747	40.77759	-73.9749	40.77777	-73.975	40.77814	-73.9747											
90	57	49	14		40.77769	-73.9751	40.77776	-73.9749	40.77777	-73.975	40.77791	-73.9749										40.77769	-73.9751	40.77776	-73.9749	40.77777	-73.975	40.77798	-73.9748											
21	56	52	14		40.77778	-73.975	40.77776	-73.9749	40.77777	-73.975	40.77769	-73.975										40.77778	-73.975	40.77776	-73.9749	40.77776	-73.975	40.77777	-73.9748											
45	57	55	14		40.77801	-73.9748	40.77761	-73.9749	40.77777	-73.975	40.77769	-73.9749										40.77801	-73.9748	40.77761	-73.9749	40.77776	-73.975	40.77771	-73.9749											
17	57	58	14		40.77788	-73.9749	40.77762	-73.9749	40.77777	-73.975	40.7778	-73.9749										40.77788	-73.9749	40.77762	-73.9749	40.77775	-73.975	40.778	-73.9746											
11	55	61	14		40.77802	-73.9748	40.77763	-73.9749	40.77776	-73.975	40.778	-73.9746										40.77802	-73.9748	40.77763	-73.9749	40.77774	-73.975													
167	55	64	14		40.77786	-73.9749	40.77764	-73.9749	40.77776	-73.975												40.77786	-73.9749	40.77764	-73.9749	40.77775	-73.975													
95	58	67	14		40.77776	-73.975	40.77765	-73.9749	40.77775	-73.975												40.77776	-73.975	40.77765	-73.9749	40.77776	-73.975													
16	58	70	14		40.77814	-73.9747	40.77765	-73.9749	40.77776	-73.975												40.77814	-73.9747	40.77765	-73.9749	40.77776	-73.975													
					40.77792	-73.9749	40.77766	-73.9748	40.77776	-73.975												40.77792	-73.9749	40.77766	-73.9748	40.77776	-73.975													
					40.77769	-73.975	40.77767	-73.9748	40.77776	-73.975												40.77769	-73.975	40.77767	-73.9748	40.77776	-73.975													
					40.77804	-73.9748	40.77768	-73.9748	40.77776	-73.975												40.77804	-73.9748	40.77768	-73.9748	40.77775	-73.975													
					40.77789	-73.9749	40.77769	-73.9748	40.77775	-73.975												40.77789	-73.9749	40.77769	-73.9748	40.77775	-73.975													
					40.77787	-73.9749	40.77777	-73.9748														40.77787	-73.9749	40.77777	-73.9748															
					40.77768	-73.975	40.77777	-73.9748														40.77768	-73.975	40.77777	-73.9748															
					40.77775	-73.975	40.77771	-73.9748														40.77775	-73.975	40.77771	-73.9748															
					40.77767	-73.9751	40.77772	-73.9748														40.77767	-73.9751	40.77772	-73.9748															
					40.77765	-73.9751	40.77773	-73.9748														40.77765	-73.9751	40.77773	-73.9748															
					40.77808	-73.9747	40.77774	-73.9748														40.77808	-73.9747	40.77774	-73.9748															
					40.77789	-73.9749	40.77775	-73.9748														40.77789	-73.9749	40.77775	-73.9748															